Chapter 14

Sets, Functions and Metric Spaces

14.1 Functions and sets

14.1.1 The function concept

Definition 14.1 Let us consider two sets \mathcal{A} and \mathcal{B} whose elements may be any objects whatsoever. Suppose that with each element $x \in \mathcal{A}$ there is associated, in some manner, an element $y \in \mathcal{B}$ which we denote by y = f(x).

- Then f is said to be a function from A to B or a mapping of A into B.
- 2. If $\mathcal{E} \subset \mathcal{A}$ then $f(\mathcal{E})$ is defined to be the set of all elements f(x), $x \in \mathcal{E}$ and it is called the image of \mathcal{E} under f. The notations $f(\mathcal{A})$ is called the **range** of f (evidently, that $f(\mathcal{A}) \subseteq \mathcal{B}$). If $f(\mathcal{A}) = \mathcal{B}$ we say that f maps \mathcal{A} onto \mathcal{B} .
- 3. For $\mathcal{D} \subset \mathcal{B}$ the notation $f^{-1}(\mathcal{D})$ denotes the set of all $x \in \mathcal{A}$ such that $f(x) \in \mathcal{B}$. We call $f^{-1}(\mathcal{D})$ the **inverse image** of \mathcal{D} under f. So, if $y \in \mathcal{D}$ then $f^{-1}(y)$ is the set of all $x \in \mathcal{A}$ such that f(x) = y. If for each $y \in \mathcal{B}$ the set $f^{-1}(y)$ consists of at most one element of \mathcal{A} then f is said to be **one-to-one mapping** of \mathcal{A} to \mathcal{B} .

The one-to-one mapping f means that $f(x_1) \neq f(x_2)$ if $x_1 \neq x_2$ for any $x_1, x_2 \in \mathcal{A}$. We often will use the following notation for the mapping f:

$$f: \mathcal{A} \to \mathcal{B} \tag{14.1}$$

If, in particular, $\mathcal{A} = \mathbb{R}^n$ and $\mathcal{B} = \mathbb{R}^m$ we will write

$$f:\mathbb{R}^n \to \mathbb{R}^m \tag{14.2}$$

Definition 14.2 If for two sets \mathcal{A} and \mathcal{B} there exists an one-to-one mapping then we say that these sets are **equivalent** and we write

$$\overline{\mathcal{A} \sim \mathcal{B}} \tag{14.3}$$

Claim 14.1 The relation of equivalency (\sim) clearly has the following properties:

- a) it is reflexive, i.e., $\mathcal{A} \sim \mathcal{A}$;
- **b)** it is symmetric, i.e., if $\mathcal{A} \sim \mathcal{B}$ then $\mathcal{B} \sim \mathcal{A}$;
- c) it is transitive, i.e., if $\mathcal{A} \sim \mathcal{B}$ and $\mathcal{B} \sim \mathcal{C}$ then $\mathcal{A} \sim \mathcal{C}$.

14.1.2 Finite, countable and uncountable sets

Denote by \mathcal{J}_n the set of positive numbers 1, 2, ..., n, that is,

$$\mathcal{J}_n = \{1, 2, ..., n\}$$

and by \mathcal{J} we will denote the set of all positive numbers, namely,

$$\mathcal{J} = \{1, 2, \ldots\}$$

Definition 14.3 For any \mathcal{A} we say:

1. \mathcal{A} is finite if

$$\mathcal{A} \sim \mathcal{J}_n$$

for some finite n (the **empty set** \emptyset , which does not contain any element, is also considered as finite);

2. A is countable (enumerable or denumerable) if

 $\mathcal{A} \sim \mathcal{J}$

3. A is uncountable if it is neither finite nor countable;

4. A is at most countable if it is both finite or countable.

Evidently that if \mathcal{A} is infinite then it is equivalent to one of its subsets. Also it is clear that any infinite subset of a countable set is countable.

Definition 14.4 By a sequence we mean a function f defined on the set \mathcal{J} of all positive integers. If $x_n = f(n)$ it is customarily to denote the corresponding sequence by

 $x_n \} := \{x_1, x_2, \dots\}$

(sometimes, this sequence starts with x_0 but not with x_1).

Claim 14.2

- 1. The set \mathcal{N} of all integers is countable;
- 2. The set Q of all rational numbers is countable;
- 3. The set \mathbb{R} of all real numbers is uncountable.

14.1.3 Algebra of sets

Definition 14.5 Let \mathcal{A} and Ω be sets. Suppose that with each element $\alpha \in \mathcal{A}$ there is associated a subset $\mathcal{E}_{\alpha} \subset \Omega$. Then

a) The **union** of the sets \mathcal{E}_{α} is defined to be the set \mathcal{S} such that $x \in S$ if and only if $x \in \mathcal{E}_{\alpha}$ at least for one $\alpha \in \mathcal{A}$. It will be denoted by

$$\mathcal{S} := \bigcup_{\alpha \in A} \mathcal{E}_{\alpha} \tag{14.4}$$

If \mathcal{A} consists of all integers (1, 2, ..., n), that means, $\mathcal{A} = \mathcal{J}_n$, we will use the notation

$$\mathcal{S} := \bigcup_{\alpha=1}^{n} \mathcal{E}_{\alpha} \tag{14.5}$$

and if \mathcal{A} consists of all integers (1, 2, ...), that means, $\mathcal{A} = \mathcal{J}$, we will use the notation

$$\mathcal{S} := \bigcup_{\alpha=1}^{\infty} \mathcal{E}_{\alpha} \tag{14.6}$$

b) The **intersection** of the sets \mathcal{E}_{α} is defined as the set \mathcal{P} such that $x \in \mathcal{P}$ if and only if $x \in \mathcal{E}_{\alpha}$ for every $\alpha \in \mathcal{A}$. It will be denoted by

$$\mathcal{S} := \bigcap_{\alpha \in \mathcal{A}} \mathcal{E}_{\alpha} \tag{14.7}$$

If \mathcal{A} consists of all integers (1, 2, ..., n), that means, $\mathcal{A} = \mathcal{J}_n$, we will use the notation

$$\mathcal{S} := \bigcap_{\alpha=1}^{n} \mathcal{E}_{\alpha} \tag{14.8}$$

and if \mathcal{A} consists of all integers (1, 2, ...), that means, $\mathcal{A} = \mathcal{J}$, we will use the notation

$$\mathcal{S} := \bigcap_{\alpha=1}^{\infty} \mathcal{E}_{\alpha} \tag{14.9}$$

If for two sets \mathcal{A} and \mathcal{B} we have $\mathcal{A} \cap \mathcal{B} = \emptyset$, we say that these two sets are **disjoint**.

c) The complement of \mathcal{A} relative to \mathcal{B} , denoted by $\mathcal{B} - \mathcal{A}$, is defined to be the set

$$\mathcal{B} - \mathcal{A} := \{ x : x \in \mathcal{B}, \ but \ x \notin \mathcal{A} \}$$
(14.10)

The sets $\mathcal{A} \cup \mathcal{B}$, $\mathcal{A} \cap \mathcal{B}$ and $\mathcal{B} - \mathcal{A}$ are illustrated at Fig.14.1.

Using these graphic illustrations it is possible easily to prove the following set-theoretical identities for union and intersection.

Proposition 14.1

1.

$$\mathcal{A} \cup (\mathcal{B} \cup \mathcal{C}) = (\mathcal{A} \cup \mathcal{B}) \cup \mathcal{C}, \ \mathcal{A} \cap (\mathcal{B} \cap \mathcal{C}) = (\mathcal{A} \cap \mathcal{B}) \cap \mathcal{C}$$



Figure 14.1: Two sets relations.



if and only if $\mathcal{B} \subseteq \mathcal{A}$.

8.

$$\mathcal{A} \subset \mathcal{A} \cup \mathcal{B}, \ \mathcal{A} \cap \mathcal{B} \subset \mathcal{A}$$

9.

$$\mathcal{A}\cuparnothing=\mathcal{A},\ \mathcal{A}\caparnothing=arnothing$$

10.

$$\mathcal{A} \cup \mathcal{B} = \mathcal{B}, \ \mathcal{A} \cap \mathcal{B} = \mathcal{A}$$

if $\mathcal{A} \subset \mathcal{B}$.

The next relations generalize the previous unions and intersections to arbitrary ones.

Proposition 14.2

1. Let $f : S \to T$ be a function and \mathcal{A}, \mathcal{B} any any subsets of S. Then

$$f\left(\mathcal{A}\cup\mathcal{B}\right)=f\left(\mathcal{A}\right)\cup f\left(\mathcal{B}\right)$$

2. For any $\mathcal{Y} \subseteq \mathcal{T}$ define $f^{-1}(\mathcal{Y})$ as the largest subset of S which f maps into Y. Then

a)

$$\mathcal{X}\subseteq f^{-1}\left(f\left(\mathcal{X}\right)\right)$$

b)

and

$$f\left(f^{-1}\left(\mathcal{Y}\right)\right)\subseteq\mathcal{Y}$$

if and only if
$$\mathcal{T} = f(\mathcal{S})$$
.

c)

$$f^{-1}\left(\mathcal{Y}_{1}\cup\mathcal{Y}_{2}\right)=f^{-1}\left(\mathcal{Y}_{1}\right)\cup f^{-1}\left(\mathcal{Y}_{2}\right)$$

d)

$$f^{-1}\left(\mathcal{Y}_{1} \cap \mathcal{Y}_{2}\right) = f^{-1}\left(\mathcal{Y}_{1}\right) \cap f^{-1}\left(\mathcal{Y}_{2}\right)$$

e)

$$f^{-1}(\mathcal{T} - \mathcal{Y}) = \mathcal{S} - f^{-1}(\mathcal{Y})$$

and for subsets $\mathcal{B} \subseteq \mathcal{A} \subseteq \mathcal{S}$ it follows that

$$f(\mathcal{A} - \mathcal{B}) = f(\mathcal{A}) - f(\mathcal{B})$$

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14.2 Metric spaces

14.2.1 Metric definition and examples of metrics

Definition 14.6 A set \mathcal{X} , whose elements we shall call points, is said to be a **metric space** if with any two points p and q of \mathcal{X} there is associated a real number d(p,q), called a **distance** between p and q, such that

a)

$$d(p,q) > 0 \text{ if } p \neq q d(p,p) = 0$$
(14.11)

b)

$$d(p,q) = d(q,p)$$
(14.12)

c) for any $r \in \mathcal{X}$ the following "triangle inequality" holds:

$$d(p,q) \le d(p,r) + d(r,q)$$
 (14.13)

Any function with these properties is called a **distance function** or a **metric**.

Example 14.1 The following functions are metrics:

- 1. For any p, q from the **Euclidian space** \mathbb{R}^n
 - a) the Euclidian metric:

$$d(p,q) = \|p - q\|$$
(14.14)

b) the discrete metric:

$$d(p,q) = \begin{cases} 0 & \text{if } p = q \\ 1 & \text{if } p \neq q \end{cases}$$
(14.15)

c) the weighted metric:

$$d(p,q) = \|p-q\|_Q := \sqrt{(p-q)^{\mathsf{T}} Q(p-q)}$$

$$Q = Q^{\mathsf{T}} > 0$$
(14.16)

d) the module metric:

$$d(p,q) = \sum_{i=1}^{n} |p_i - q_i|$$
(14.17)

e) the Chebyshev's metric:

$$d(p,q) = \max\{|p_1 - q_1|, ..., |p_n - q_n|\}$$
(14.18)

f) the Prokhorov's metric:

$$d(p,q) = \frac{\|p-q\|}{1+\|p-q\|} \in [0,1)$$
(14.19)

2. For any z_1 and z_2 of the complex plane \mathbb{C}

$$\frac{d(z_1, z_2) = |z_1 - z_2| =}{\sqrt{\left(\operatorname{Re}\left(z_1 - z_2\right)\right)^2 + \left(\operatorname{Im}\left(z_1 - z_2\right)\right)^2}}$$
(14.20)

14.2.2 Set structures

Let \mathcal{X} be a metric space. All points and sets mentioned below will be understood to be elements and subsets of \mathcal{X} .

Definition 14.7

a) A **neighborhood** of a point x is a set $\mathcal{N}_r(x)$ consisting of all points y such that d(x, y) < r where the number r is called the radius of $\mathcal{N}_r(x)$, that is,

$$\mathcal{N}_{r}(x) := \left\{ x \in \mathcal{X} : d(x, y) < r \right\}$$
(14.21)

- b) A point $x \in \mathcal{X}$ is a **limit point** of the set $\mathcal{E} \subset \mathcal{X}$ if every neighborhood of x contains a point $y \neq x$ such that $q \in \mathcal{E}$.
- c) If $x \in \mathcal{E}$ and x is not a limit point of then x is called an **isolated** point of \mathcal{E} .
- d) $\mathcal{E} \subset \mathcal{X}$ is closed if every limit of \mathcal{E} is a point of \mathcal{E} .

- e) A point $x \in \mathcal{E}$ is an **interior point** of \mathcal{E} if there is a neighborhood of $\mathcal{N}_r(x)$ of x such that $\mathcal{N}_r(x) \subset \mathcal{E}$.
- f) \mathcal{E} is open if every point of \mathcal{E} is an interior point of \mathcal{E} .
- g) The complement \mathcal{E}^c of \mathcal{E} is the set of all points $x \in \mathcal{X}$ such that $x \notin \mathcal{E}$.
- h) \mathcal{E} is **bounded** if there exists a real number M and a point $x \in \mathcal{E}$ such that d(x, y) < M for all $y \in \mathcal{E}$.
- i) \mathcal{E} is dense in \mathcal{X} if every point $x \in \mathcal{X}$ is a limit point of \mathcal{E} , or a point of \mathcal{E} , or both.
- *j)* \mathcal{E} is connected in \mathcal{X} if it is not a union of two nonempty separated sets, that is, \mathcal{E} can not be represented as $\mathcal{E} = \mathcal{A} \cup \mathcal{B}$ where $\mathcal{A} \neq \emptyset, \ \mathcal{B} \neq \emptyset$ and $\mathcal{A} \cap \mathcal{B} = \emptyset$.

Example 14.2 The set $J_{open}(p)$ defined as

$$J_{open} := \{ x \in \mathcal{X}, \ d(x, p) < r \}$$

is an open set but the set $J_{closed}(p)$ defined as

$$J_{closed}\left(p\right) := \left\{x \in \mathcal{X}, \ d\left(x, p\right) \le r\right\}$$

is closed.

The following claims seem to be evident and, that's why, they are given without proofs.

Claim 14.3

- 1. Every neighborhood $\mathcal{N}_r(x) \subset \mathcal{E}$ is an open set.
- 2. If x is a limit point of \mathcal{E} then every neighborhood $\mathcal{N}_r(x) \subset \mathcal{E}$ contains infinitely many points of \mathcal{E} .
- 3. A finite point set has no limit points.

Let us prove the following lemma concerning complement sets.

Lemma 14.1 Let $\{\mathcal{E}_{\alpha}\}$ be a collection (finite or infinite) of sets $\mathcal{E}_{\alpha} \subseteq \mathcal{X}$. Then

$$\left(\bigcup_{\alpha} \mathcal{E}_{\alpha}\right)^{c} = \bigcap_{\alpha} \mathcal{E}_{\alpha}^{c}$$
(14.22)

Proof. If $x \in \left(\bigcup_{\alpha} \mathcal{E}_{\alpha}\right)^{c}$ then, evidently, $x \notin \bigcup_{\alpha} \mathcal{E}_{\alpha}$ and, hence, $x \notin \mathcal{E}_{\alpha}$ for any α . This means that $x \in \bigcap_{\alpha} \mathcal{E}_{\alpha}^{c}$. Thus,

$$\left(\bigcup_{\alpha} \mathcal{E}_{\alpha}\right)^{c} \subseteq \bigcap_{\alpha} \mathcal{E}_{\alpha}^{c}$$
(14.23)

Conversely, if $x \in \bigcap_{\alpha} \mathcal{E}_{\alpha}^{c}$ then $x \in \mathcal{E}_{\alpha}^{c}$ for every α and, hence, $x \notin \bigcup_{\alpha} \mathcal{E}_{\alpha}$. So, $x \in \left(\bigcup_{\alpha} \mathcal{E}_{\alpha}\right)^{c}$ that implies

$$\bigcap_{\alpha} \mathcal{E}_{\alpha}^{c} \subseteq \left(\bigcup_{\alpha} \mathcal{E}_{\alpha}\right)^{c}$$
(14.24)

Combining (14.23) and (14.24) gives (14.22). Lemma is proven. ■ This lemma provides the following corollaries.

Corollary 14.1

- a) A set \mathcal{E} is open if and only if its complement \mathcal{E}^c is closed.
- b) A set \mathcal{E} is closed if and only if its complement \mathcal{E}^c is open.
- c) For any collection $\{\mathcal{E}_{\alpha}\}$ of open sets \mathcal{E}_{α} the set $\bigcup_{\alpha} \mathcal{E}_{\alpha}$ is open.
- d) For any collection $\{\mathcal{E}_{\alpha}\}$ of closed sets \mathcal{E}_{α} the set $\bigcap_{\alpha} \mathcal{E}_{\alpha}^{c}$ is closed.
- e) For any finite collection $\{\mathcal{E}_1, ..., \mathcal{E}_n\}$ of open sets \mathcal{E}_α the set $\bigcap_{\alpha} \mathcal{E}_\alpha^c$ is open too.
- f) For any finite collection $\{\mathcal{E}_1, ..., \mathcal{E}_n\}$ of closed sets \mathcal{E}_{α} the set $\bigcup_{\alpha} \mathcal{E}_{\alpha}$ is closed too.

Definition 14.8 Let \mathcal{X} be a metric space and $\mathcal{E} \subset \mathcal{X}$. Denote by \mathcal{E}' the set of all limit points of \mathcal{E} . Then the set $cl\mathcal{E}$ defined as

$$\boxed{\mathrm{cl}\mathcal{E} := \mathcal{E} \cup \mathcal{E}'} \tag{14.25}$$

is called the **closure** or \mathcal{E} .

The next properties seem to be logical consequences of this definition.

Proposition 14.3 If \mathcal{X} be a metric space and $\mathcal{E} \subset \mathcal{X}$, then

- a) $cl\mathcal{E}$ is closed;
- b) $\mathcal{E} = cl\mathcal{E}$ if and only if \mathcal{E} is closed;
- c) $cl\mathcal{E} \subset \mathcal{P}$ for every closed set $\mathcal{P} \subset \mathcal{X}$ such that $\mathcal{E} \subset \mathcal{P}$;
- d) If is a nonempty set of real numbers which is bounded above, i.e., $\emptyset \neq \mathcal{E} \subset \mathbb{R}$ and $y := \sup \mathcal{E} < \infty$. Then $y \in \operatorname{cl}\mathcal{E}$ and, hence, $y \in \mathcal{E}$ if \mathcal{E} is closed.

Proof.

a) If $x \in \mathcal{X}$ and $y \notin cl\mathcal{E}$ then x is neither a point of \mathcal{E} nor a limit point of \mathcal{E} . Hence x has a neighborhood which does not intersect \mathcal{E} . Therefore the complement \mathcal{E}^c of \mathcal{E} is an open set. So, $cl\mathcal{E}$ is closed.

b) If $\mathcal{E} = \mathrm{cl}\mathcal{E}$ then by a) it follows that \mathcal{E} is closed. If \mathcal{E} is closed then for \mathcal{E}' , defined in (14.8), we have that $\mathcal{E}' \subset \mathcal{E}$. Hence, $\mathcal{E} = \mathrm{cl}\mathcal{E}$.

c) \mathcal{P} is closed and $\mathcal{P} \supset \mathcal{E}$ (defined in (14.8)) then $\mathcal{P} \supset \mathcal{P}'$ and, hence, $\mathcal{P} \supset \mathcal{E}'$. Thus $\mathcal{P} \supset cl\mathcal{E}$.

d) If $y \in \mathcal{E}$ then $y \in cl\mathcal{E}$. Assume $y \notin \mathcal{E}$. Then for any $\varepsilon > 0$ there exists a point $x \in \mathcal{E}$ such that $y - \varepsilon < x < y$, for otherwise $(y - \varepsilon)$ would be an upper bound of \mathcal{E} that contradicts to the supposition $\sup \mathcal{E} = y$. Thus y is a limit point of \mathcal{E} . Hence, $y \in cl\mathcal{E}$.

The proposition is proven. \blacksquare

Definition 14.9 Let \mathcal{E} be a set of a metric space \mathcal{X} . A point $x \in \mathcal{E}$ is called **a boundary point** of \mathcal{E} if any neighborhood $\mathcal{N}_r(x)$ of this point contains at least one point of \mathcal{E} and at least one point of $\mathcal{X} - \mathcal{E}$. The set of all boundary points of \mathcal{E} is called the **boundary of the set** \mathcal{E} and is denoted by $\partial \mathcal{E}$.

It is not difficult to verify that

$$\partial \mathcal{E} = \mathrm{cl}\mathcal{E} \cap \mathrm{cl}(\mathcal{X} - \mathcal{E})$$
(14.26)

Denoting by

$$int\mathcal{E} := \mathcal{E} - \partial \mathcal{E}$$
(14.27)

the set of all internal points of the set \mathcal{E} , it is easily verify that

$$int \mathcal{E} = \mathcal{X} - cl (\mathcal{X} - \mathcal{E})$$

$$int (\mathcal{X} - \mathcal{E}) = \mathcal{X} - cl \mathcal{E}$$

$$int (int \mathcal{E}) = int \mathcal{E}$$

If $cl \mathcal{E} \cap cl \mathcal{D} = \emptyset$ then $\partial (\mathcal{E} \cup \mathcal{D}) = \partial \mathcal{E} \cup \partial \mathcal{D}$
(14.28)

14.2.3 Compact sets

Definition 14.10

By an open cover of a set *E* in a metric space *X* we mean a collection {*G*_α} of open subsets of *X* such that

$$\mathcal{E} \subset \bigcup_{\alpha} \mathcal{G}_{\alpha} \tag{14.29}$$

2. A subset \mathcal{K} of a metric space \mathcal{X} is said to be **compact** if every open cover of \mathcal{K} contains a finite subcover, more exactly, there are a finite number of indices $\alpha_1, ..., \alpha_n$ such that

$$\mathcal{E} \subset \mathcal{G}_{\alpha_1} \cup \cdots \cup \mathcal{G}_{\alpha_n}$$
(14.30)

Remark 14.1 Evidently that every finite set is compact.

Theorem 14.1 A set $\mathcal{K} \subset \mathcal{Y} \subset \mathcal{X}$ is a compact relative to \mathcal{X} if and only if \mathcal{K} is a compact relative to \mathcal{Y} .

Proof. Necessity. Suppose \mathcal{K} is a compact relative to \mathcal{X} . Hence, by the definition (14.30) there exists its finite subcover such that

$$\mathcal{K} \subset \mathcal{G}_{\alpha_1} \cup \cdots \cup \mathcal{G}_{\alpha_n} \tag{14.31}$$

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where \mathcal{G}_{α_i} is an open set with respect to \mathcal{X} . On the other hand $\mathcal{K} \subset \bigcup_{\alpha} \mathcal{V}_{\alpha}$ where $\{\mathcal{V}_{\alpha}\}$ is a collection of sets open with respect to \mathcal{Y} . But any open set \mathcal{V}_{α} can be represented as $\mathcal{V}_{\alpha} = \mathcal{Y} \cap \mathcal{G}_{\alpha}$. So, (14.31) implies

$$\mathcal{K} \subset \mathcal{V}_{\alpha_1} \cup \dots \cup \mathcal{V}_{\alpha_n} \tag{14.32}$$

Sufficiency. Conversely, if \mathcal{K} is a compact relative to \mathcal{Y} then there exists a finite collection $\{\mathcal{V}_{\alpha}\}$ of open sets in \mathcal{Y} such that (14.32) holds. Putting $\mathcal{V}_{\alpha} = \mathcal{Y} \cap \mathcal{G}_{\alpha}$ for a special choice of indices $\alpha_1, ..., \alpha_n$ it follows that $\mathcal{V}_{\alpha} \subset \mathcal{G}_{\alpha}$ that implies (14.31). Theorem is proven.

Theorem 14.2 Compact sets of metric spaces are closed.

Proof. Suppose \mathcal{K} is a compact subset of a metric space \mathcal{X} . Let $x \in \mathcal{X}$ but $x \notin \mathcal{K}$ and $y \in \mathcal{K}$. Consider the neighborhoods $\mathcal{N}_r(x)$ $\mathcal{N}_r(y)$ of these points with $r < \frac{1}{2}d(x,y)$. Since \mathcal{K} is a compact there are finitely many points $y_1, ..., y_n$ such that

$$\mathcal{K} \subset \mathcal{N}_r(y_1) \cup \cdots \cup \mathcal{N}_r(y_n) = \mathcal{N}$$

If $\mathcal{V} = \mathcal{N}_{r_1}(x) \cap \cdots \cap \mathcal{N}_{r_n}(x)$, then evidently \mathcal{V} is a neighborhood of x which does not intersect \mathcal{N} and, hence, $\mathcal{V} \subset \mathcal{K}^c$. So, x is an interior point of \mathcal{K}^c . Theorem is proven.

The following two propositions seem to be evident.

Proposition 14.4

- 1. Closed subsets of compact sets are compacts too.
- 2. If \mathcal{F} is closed and \mathcal{K} is compact then $\mathcal{F} \cap \mathcal{K}$ is compact.

Theorem 14.3 If \mathcal{E} is an infinite subset of a compact set \mathcal{K} then \mathcal{E} has a limit point in \mathcal{K} .

Proof. If no point of \mathcal{K} were a limit point of \mathcal{E} then $y \in \mathcal{K}$ would have a neighborhood $\mathcal{N}_r(y)$ which contains at most one point of \mathcal{E} (namely, y if $y \in \mathcal{E}$). It is clear that no finite subcollection $\{\mathcal{N}_{r_k}(y)\}$ can cover \mathcal{E} . The same is true of \mathcal{K} since $\mathcal{E} \subset \mathcal{K}$. But this contradicts the compactness of \mathcal{K} . Theorem is proven.

The next theorem explains the compactness property especially in \mathbb{R}^n and is often applied in a control theory analysis.

Theorem 14.4 If a set $\mathcal{E} \subset \mathbb{R}^n$ then the following three properties are equivalent:

- a) \mathcal{E} is closed and bounded.
- b) \mathcal{E} is compact.
- c) Every infinite subset of \mathcal{E} has a limit point in \mathcal{E} .

Proof. It is the consequence of all previous theorems and propositions and stay for readers consideration. The details of the proof can be found in Chapter 2 of (Rudin 1976). \blacksquare

Remark 14.2 Notice that properties b) and c) are equivalent in any metric space, but a) not.

14.2.4 Convergent sequences in metric spaces

Convergence

Definition 14.11 A sequence $\{x_n\}$ in a metric space \mathcal{X} is said to converge if there is a point $x \in \mathcal{X}$ for which for any $\varepsilon > 0$ there exists an integer n_{ε} such that $n \ge n_{\varepsilon}$ implies that $d(x_n, x) < \varepsilon$. Here $d(x_n, x)$ is the metric (distance) in \mathcal{X} . In this case we say that $\{x_n\}$ converges to x, or that x is a limit of $\{x_n\}$, and we write

$$\lim_{n \to \infty} x_n = x \text{ or } x_n \xrightarrow[n \to \infty]{} x$$
(14.33)

If $\{x_n\}$ does not converge, it is usually said to **diverge**.

Example 14.3 The sequence $\{1/n\}$ converge to 0 in \mathbb{R} , but fails to converge in $\mathbb{R}_+ := \{x \in \mathbb{R} \mid x > 0\}.$

Theorem 14.5 Let $\{x_n\}$ be a sequence in a metric space \mathcal{X} .

1. $\{x_n\}$ converges to $x \in \mathcal{X}$ if and only if every neighborhood $\mathcal{N}_{\varepsilon}(x)$ of x contains all but (excluding) finitely many of the terms of $\{x_n\}$. 2. If $x', x'' \in \mathcal{X}$ and

$$x_n \xrightarrow[n \to \infty]{} x' \text{ and } x_n \xrightarrow[n \to \infty]{} x''$$

x' = x''

then

- 3. If $\{x_n\}$ converges then $\{x_n\}$ is bounded.
- 4. If $\mathcal{E} \subset \mathcal{X}$ and x is a limit point of \mathcal{E} then there is a sequence $\{x_n\}$ in \mathcal{E} such that $x = \lim_{n \to \infty} x_n$.

Proof.

1. a) Necessity. Suppose $x_n \xrightarrow[n \to \infty]{n \to \infty} x$ and let $\mathcal{N}_{\varepsilon}(x)$ (for some $\varepsilon > 0$) be a neighborhood of x. The conditions $d(y, x) < \varepsilon, y \in \mathcal{X}$ imply $y \in \mathcal{N}_{\varepsilon}(x)$. Corresponding to this ε there exists a number n_{ε} such that for any $n \ge n_{\varepsilon}$ it follows that $d(x_n, x) < \varepsilon$. Thus, $x_n \in \mathcal{N}_{\varepsilon}(x)$. So, all x_n are bounded.

b) Sufficiency. Conversely, suppose every neighborhood of x contains all but finitely many of the terms of $\{x_n\}$. Fixing $\varepsilon > 0$ denoting by $\mathcal{N}_{\varepsilon}(x)$ the set of all $y \in \mathcal{X}$ such that $d(y, x) < \varepsilon$. By the assumption there exists n_{ε} such that for any $n \ge n_{\varepsilon}$ it follows that $x_n \in \mathcal{N}_{\varepsilon}(x)$. Thus $d(x_n, x) < \varepsilon$ if $n \ge n_{\varepsilon}$ and, hence, $x_n \xrightarrow[n \to \infty]{} x$.

- 2. For the given $\varepsilon > 0$ there exist integers n' and n'' such that $n \ge n'$ implies $d(x_n, x') < \varepsilon/2$ and $n \ge n''$ implies $d(x_n, x'') < \varepsilon/2$. So, for $n \ge \max\{n', n''\}$ it follows $d(x', x'') \le d(x', x_n) + d(x_n, x'') < \varepsilon$. Taking ε small enough we conclude that d(x', x'') = 0.
- 3. Suppose $x_n \xrightarrow[n \to \infty]{} x$. Then, evidently there exists an integer n_0 such that for all $n \ge n_0$ we have that $d(x_n, x) < 1$. Define $r := \max\{1, d(x_1, x), ..., d(x_{n_0}, x)\}$. Then $d(x_n, x) < r$ for all n = 1, 2, ...
- 4. For any integer n = 1, 2, ... there exists a point $x_n \in \mathcal{E}$ such that $d(x_n, x) < 1/n$. For any given $\varepsilon > 0$ define n_{ε} such that $\varepsilon n_{\varepsilon} > 1$. Then for $n \ge n_{\varepsilon}$ one has $d(x_n, x) < 1/n < \varepsilon$ that means that $x_n \xrightarrow[n \to \infty]{} x$.

This completes the proof. \blacksquare

Subsequences

Definition 14.12 Given a sequence $\{x_n\}$ let us consider a sequence $\{n_k\}$ of positive integers satisfying $n_1 < n_2 < \cdots$. Then the sequence $\{x_{n_k}\}$ is called a **subsequence** of $\{x_n\}$.

Claim 14.4 If a sequence $\{x_n\}$ converges to x then any subsequence $\{x_{n_k}\}$ of $\{x_n\}$ converges to the same limit point x.

Proof. This result can be easily proven by contradiction. Indeed, assuming that two different subsequences $\{x_{n_k}\}$ and $\{x_{n_j}\}$ have different limit points x' and x'', then it follows that there exists $0 < \varepsilon < d(x', x'')$ and a number k_{ε} such that for all $k \ge k_{\varepsilon}$ we shall have: $d(x_{n_k}, x_{n_j}) > \varepsilon$ that is in the contradiction with the assumption that $\{x_n\}$ converges.

Theorem 14.6

- **a)** If $\{x_n\}$ is a sequence in a compact metric space \mathcal{X} then it obligatory contains some subsequence $\{x_{n_k}\}$ convergent to a point of \mathcal{X} .
- **b)** Any bounded sequence in \mathbb{R}^n contains a convergent subsequent.

Proof.

a) Let \mathcal{E} be the range of $\{x_n\}$. If $\{x_n\}$ converges then the desired subsequence is this sequence itself. Suppose that $\{x_n\}$ diverges. If \mathcal{E} is finite then obligatory there is a point $x \in \mathcal{E}$ and numbers $n_1 < n_2 < \cdots$ such that $x_1 = x_2 = \cdots = x$. The subsequence $\{x_{n_k}\}$ so obtained converges evidently to x. If \mathcal{E} is infinite then by Theorem (14.3) \mathcal{E} has a limit point $x \in \mathcal{X}$. Choose n_1 so that $d(x_{n_1}, x) < 1$, and, hence, there are integer $n_i > n_{i-1}$ such that $d(x_{n_i}, x) < 1/i$. This means that x_{n_i} converges to x.

b) This follows from a) since Theorem (14.4) implies that every bounded subset of \mathbb{R}^n lies in a compact sunset of \mathbb{R}^n .

Theorem is proven. \blacksquare

Cauchy sequences

Definition 14.13 A sequence $\{x_n\}$ in a metric space \mathcal{X} is said to be a **Cauchy (fundamental) sequence** if for every $\varepsilon > 0$ there is an integer n_{ε} such that $d(x_n, x_m) < \varepsilon$ if both $n \ge n_{\varepsilon}$ and $m \ge n_{\varepsilon}$.

Defining the *diameter* of \mathcal{E} as

diam
$$\mathcal{E} := \sup_{x,y \in \mathcal{E}} d(x,y)$$
 (14.34)

one may conclude that if $\mathcal{E}_{n_{\varepsilon}}$ consists of the points $\{x_{n_{\varepsilon}}, x_{n_{\varepsilon}+1}, ...\}$ then $\{x_n\}$ is a Cauchy sequence if and only if

$$\lim_{n_{\varepsilon} \to \infty} \operatorname{diam} \mathcal{E} = 0 \tag{14.35}$$

Theorem 14.7

a) If $cl\mathcal{E}$ is the closure of a set \mathcal{E} in a metric space \mathcal{X} then

$$diam \mathcal{E} = diam cl\mathcal{E}$$
(14.36)

b) If \mathcal{K}_n is a sequence of compact sets in \mathcal{X} such that $\mathcal{K}_n \supset \mathcal{K}_{n-1}$ (n = 2, 3, ...) then the set $\mathcal{K} := \bigcap_{n=1}^{\infty} \mathcal{K}_n$ consists exactly of one point.

Proof.

a) Since $\mathcal{E} \subseteq cl\mathcal{E}$ it follows that

$$\operatorname{diam} \mathcal{E} \le \operatorname{diam} \operatorname{cl} \mathcal{E} \tag{14.37}$$

Fix $\varepsilon > 0$ and select $x, y \in cl\mathcal{E}$. By the definition (14.25) there are to points $x', y' \in \mathcal{E}$ such that both $d(x, x') < \varepsilon$ and $d(y, y') < \varepsilon$ that implies

$$d(x, y) \le d(x, x') + d(x', y') + d(y', y) < 2\varepsilon + d(x', y') \le 2\varepsilon + \operatorname{diam} \mathcal{E}$$

As the result, we have

diam
$$\mathrm{cl}\mathcal{E} \leq 2\varepsilon + \mathrm{diam}\mathcal{E}$$

and since ε is arbitrary it follows that

$$\operatorname{diam} \operatorname{cl} \mathcal{E} \le \operatorname{diam} \mathcal{E} \tag{14.38}$$

The inequalities (14.37) and (14.38) give (14.36).

b) If \mathcal{K} contains more then one point then diam $\mathcal{K} > 0$. But for each n we have that $\mathcal{K}_n \supset \mathcal{K}$, so that diam $\mathcal{K}_n \ge \text{diam } \mathcal{K}$. This contradict that diam $\mathcal{K}_n \xrightarrow[n \to \infty]{} 0$.

Theorem is proven. \blacksquare

The next theorem explains the importance of fundamental sequence in the analysis of metric spaces.

Theorem 14.8

- a) Every convergent sequence $\{x_n\}$ given in a metric space \mathcal{X} is a Cauchy sequence.
- b) If \mathcal{X} is a compact metric space and if $\{x_n\}$ is a Cauchy sequence in \mathcal{X} then $\{x_n\}$ converges to some point in \mathcal{X} .
- c) In \mathbb{R}^n a sequence converges if and only if it is a Cauchy sequence.

Usually, the claim c) is referred to as the **Cauchy criterion**.

Proof.

a) If $x_n \to x$ then for any $\varepsilon > 0$ there exists an integer n_{ε} such that $d(x_n, x) < \varepsilon$ for all $n \ge n_{\varepsilon}$. So, $d(x_n, x_m) \le d(x_n, x) + d(x, x_m) < 2\varepsilon$ if $n, m \ge n_{\varepsilon}$. Thus $\{x_n\}$ is a Cauchy sequence.

b) Let $\{x_n\}$ be a Cauchy sequence and the set $\mathcal{E}_{n_{\varepsilon}}$ contains the points $x_{n_{\varepsilon}}, x_{n_{\varepsilon}+1}, x_{n_{\varepsilon}+2}, \dots$. Then by Theorem (14.7) and in view of (14.35) and (14.36)

$$\lim_{n_{\varepsilon} \to \infty} \operatorname{diam} \, \operatorname{cl}\mathcal{E}_{n_{\varepsilon}} = \lim_{n_{\varepsilon} \to \infty} \operatorname{diam} \, \mathcal{E}_{n_{\varepsilon}} = 0 \tag{14.39}$$

Being a closed subset of the compact space \mathcal{X} each $cl\mathcal{E}_{n_{\varepsilon}}$ is compact (see Proposition 14.4). And since $\mathcal{E}_n \supset \mathcal{E}_{n+1}$ then $cl\mathcal{E}_n \supset cl\mathcal{E}_{n+1}$. By Theorem 14.7 b), there is a unique point $x \in \mathcal{X}$ which lies in $cl\mathcal{E}_n$. The expression (14.39) means that for any $\varepsilon > 0$ there exists an integer n_{ε} such that diam $cl\mathcal{E}_n < \varepsilon$ if $n \ge n_{\varepsilon}$. Since $x \in cl\mathcal{E}_n$ then $d(x, y) < \varepsilon$ for any $x \in cl\mathcal{E}_n$ that equivalent to the following: $d(x, x_n) < \varepsilon$ if $n \ge n_{\varepsilon}$. But this means that $x_n \to x$.

c) Let $\{x_n\}$ be a Cauchy sequence in \mathbb{R}^n and define $\mathcal{E}_{n_{\varepsilon}}$ like in the statement b) but with $\mathbf{x}_n \in \mathbb{R}^n$ instead of x_n . For some n_{ε} we have that diam $\mathcal{E}_{n_{\varepsilon}} < 1$. The range of $\{\mathbf{x}_n\}$ is the union of \mathcal{E}_n and the finite set $\{\mathbf{x}_1, \mathbf{x}_2, ..., \mathbf{x}_{n_{\varepsilon}-1}\}$. Hence, $\{\mathbf{x}_n\}$ is bounded and since every bounded sunset in \mathbb{R}^n has a compact closure in \mathbb{R}^n , the statement follows from the statement b).

Theorem is proven. \blacksquare

Definition 14.14 A metric space where each Cauchy sequence converges is said to be complete.

Example 14.4

- 1. By Theorem (14.8) it follows that all Euclidean spaces are complete.
- 2. The space of all rational numbers with the metric d(x, y) = |x y| is not complete.
- 3. In \mathbb{R}^n any convergent sequence is bounded but not any bounded sequence obligatory converges.

There is a special case when bounded sequence obligatory converges. Next theorem specifies such sequences.

Theorem 14.9 (Weierstrass theorem) Any monotonic sequence $\{s_n\}$ of real numbers, namely, when

- a) $\{s_n\}$ is monotonically non-decreasing: $s_n \leq s_{n+1}$;
- **b**) $\{s_n\}$ is monotonically non-increasing: $s_n \ge s_{n+1}$;

converges if and only if it is bounded.

Proof. If $\{s_n\}$ converges it is bounded by Theorem (14.5) the claim 3. Suppose that and $\{s_n\}$ is bounded, namely, $\sup s_n = s < \infty$. Then $s_n \leq s$ and for every $\varepsilon > 0$ there exists an integer n_{ε} such that $s - \varepsilon \leq s_n \leq s$ for otherwise $s - \varepsilon$ would be an upper bound for $\{s_n\}$. Since $\{s_n\}$ increases and ε is arbitrary small this means $s_n \to s$. The case $s_n \geq s_{n+1}$ is considered analogously. Theorem is proven.

Upper and lower limits in ${\mathbb R}$

Definition 14.15 Let $\{s_n\}$ be a sequence of real numbers in \mathbb{R} .

a) If for every real M there exists an integer n_M such that $s_n \ge M$ for all $n \ge n_M$ we then write

$$s_n \to \infty \tag{14.40}$$

b) If for every real M there exists an integer n_M such that $s_n \leq M$ for all $n \geq n_M$ we then write

$$s_n \to -\infty \tag{14.41}$$

c) Define the upper limit of a sequence $\{s_n\}$ as

$$\limsup_{n \to \infty} s_n := \lim_{t \to \infty} \sup_{n \ge t} s_n \tag{14.42}$$

which may be treated as a biggest limit of all possible subsequences.

d) Define the lower limit of a sequence $\{s_n\}$ as

$$\lim_{n \to \infty} \inf s_n := \lim_{t \to \infty} \inf_{n \ge t} s_n \tag{14.43}$$

which may be treated as a lowest limit of all possible subsequences.

The following theorem whose proof is quit trivial is often used in many practical problems.

Theorem 14.10 Let $\{s_n\}$ and $\{t_n\}$ be two sequences of real numbers in \mathbb{R} . Then the following properties hold:

1.

$$\liminf_{n \to \infty} s_n \le \limsup_{n \to \infty} s_n \tag{14.44}$$

2.

$$\lim_{\substack{n \to \infty \\ n \to \infty}} \sup s_n = \infty \quad if \quad s_n \to \infty$$

$$\lim_{n \to \infty} \inf s_n = -\infty \quad if \quad s_n \to -\infty$$
(14.45)

3.

$$\lim_{n \to \infty} \sup_{n \to \infty} (s_n + t_n) \le \limsup_{n \to \infty} s_n + \limsup_{n \to \infty} t_n$$
(14.46)

$$\liminf_{n \to \infty} (s_n + t_n) \ge \liminf_{n \to \infty} s_n + \liminf_{n \to \infty} t_n$$
(14.47)

5. If $\lim_{n \to \infty} s_n = s$ then

$$\liminf_{n \to \infty} s_n = \liminf_{n \to \infty} s_n = s \tag{14.48}$$

6. If $s_n \leq t_n$ for all $n \geq M$ which is fixed then

$$\limsup_{\substack{n \to \infty \\ \lim \\ n \to \infty}} s_n \leq \limsup_{\substack{n \to \infty \\ n \to \infty}} t_n \tag{14.49}$$

Example 14.5

1.

$$\limsup_{n \to \infty} \sin\left(\frac{\pi}{2}n\right) = 1, \ \liminf_{n \to \infty} \sin\left(\frac{\pi}{2}n\right) = -1$$

2.

$$\limsup_{n \to \infty} \tan\left(\frac{\pi}{2}n\right) = \infty, \ \liminf_{n \to \infty} \tan\left(\frac{\pi}{2}n\right) = -\infty$$

3. For
$$s_n = \frac{(-1)^n}{1+1/n}$$

 $\limsup_{n \to \infty} s_n = 1, \ \lim \inf_{n \to \infty} s_n = -1$

14.2.5 Continuity and function limits in metric spaces

Continuity and limits of functions

Let \mathcal{X} and \mathcal{Y} be metric spaces and $\mathcal{E} \subset \mathcal{X}$, f maps \mathcal{E} into \mathcal{Y} and $p \in \mathcal{X}$.

Definition 14.16

a) We write

$$\lim_{x \to p} f(x) = q \tag{14.50}$$

if there is a point $q \in \mathcal{Y}$ such that for every $\varepsilon > 0$ there exists a $\delta = \delta(\varepsilon, p) > 0$ for which $d_{\mathcal{Y}}(f(x), q) < \varepsilon$ for all $x \in \mathcal{E}$ for which $d_{\mathcal{X}}(x, p) < \delta$. The symbols $d_{\mathcal{Y}}$ and $d_{\mathcal{X}}$ are referred to as the distance in \mathcal{X} and \mathcal{Y} , respectively. Notice that f may be not defined at p since p may not belong to \mathcal{E} .

- **b)** If, in addition, $p \in \mathcal{E}$ and $d_{\mathcal{Y}}(f(x), f(p)) < \varepsilon$ for every $\varepsilon > 0$ and for all $x \in \mathcal{E}$ for which $d_{\mathcal{X}}(x, p) < \delta = \delta(\varepsilon)$ then f is said to be **continuous** at the point p.
- c) If f is continuous at every point of E then f is said to be continuous on E.
- **d)** If for any $x, y \in \mathcal{E} \subseteq \mathcal{X}$

$$d_{\mathcal{Y}}(f(x), f(y)) \le L_f d_{\mathcal{X}}(x, y), \ L_f < \infty$$
(14.51)

then f is said to be Lipschitz continuous on \mathcal{E} .

Remark 14.3 If p is a limit point of \mathcal{E} then f is continuous at the point p if and only if

$$\lim_{x \to p} f(x) = f(p) \tag{14.52}$$

The proof of this result follows directly from the definition above. The following properties related to continuity are evidently fulfilled.

Proposition 14.5

1. If for metric spaces $\mathcal{X}, \mathcal{Y}, \mathcal{Z}$ the following mappings are defined:

$$f: \mathcal{E} \subset \mathcal{X} \to \mathcal{Y}, \ g: f(\mathcal{E}) \to \mathcal{Z}$$

and

$$h(x) := g(f(x)), x \in \mathcal{E}$$

then h is continuous at a point $p \in \mathcal{E}$ if f is continuous at p and g is continuous at f(p).

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- 2. If $f : \mathcal{X} \to \mathbb{R}^n$ and $f(x) := (f_1(x), ..., f_n(x))$ then f is continuous if and only if all $f_i(x)$ $(i = \overline{1, n})$ are continuous.
- 3. If $f, g : \mathcal{X} \to \mathbb{R}^n$ are continuous mappings then f + g and (f, g) are continuous too on \mathcal{X} .
- 4. A mapping $f : \mathcal{X} \to \mathcal{Y}$ is continuous on \mathcal{X} if and only if $f^{-1}(\mathcal{V})$ is open (closed) in \mathcal{X} for every open (closed) set $\mathcal{V} \subset \mathcal{Y}$.

Continuity, compactness and connectedness

Theorem 14.11 If $f : \mathcal{X} \to \mathcal{Y}$ is a continuous mapping of a compact metric space \mathcal{X} into a metric space \mathcal{Y} then $f(\mathcal{X})$ is compact.

Proof. Let $\{\mathcal{V}_{\alpha}\}$ be an open cover of $f(\mathcal{X})$. By continuity of f and in view of Proposition 14.5 it follows that each of the sets $f^{-1}(\mathcal{V}_{\alpha})$ is open. By the compactness of \mathcal{X} there are finitely many indices $\alpha_1, ..., \alpha_n$ such that

$$\mathcal{X} \subset \bigcup_{i=1}^{n} f^{-1}\left(\mathcal{V}_{\alpha_{i}}\right) \tag{14.53}$$

Since $f(f^{-1}(\mathcal{E})) \subset \mathcal{E}$ for any $\mathcal{E} \subset \mathcal{Y}$ it follows that (14.53) implies that $f(\mathcal{X}) \subset \bigcup_{\alpha=1}^{n} \mathcal{V}_{\alpha_i}$. This completes the proof.

Corollary 14.2 If $f : \mathcal{X} \to \mathbb{R}^n$ is a continuous mapping of a compact metric space \mathcal{X} into \mathbb{R}^n then $f(\mathcal{X})$ is closed and bounded, that is, it contains its all limit points and $||f(x)|| \leq M < \infty$ for any $x \in \mathcal{X}$.

Proof. It follows directly from Theorems 14.11 and 14.4. \blacksquare The next theorem is particular important when f is real.

Theorem 14.12 (Weierstrass theorem) If $f : \mathcal{X} \to \mathbb{R}^n$ is a continuous mapping of a compact metric space \mathcal{X} into \mathbb{R} and

$$M = \sup_{x \in \mathcal{X}} f(x), \ m = \inf_{x \in \mathcal{X}} f(x)$$

then there exist points $x_M, x_m \in \mathcal{X}$ such that

$$M = f(x_M), \ m = f(x_m)$$

This means that f attains its maximum (at x_M) and its minimum (at x_m), that is,

$$M = \sup_{x \in \mathcal{X}} f(x) = \max_{x \in \mathcal{X}} f(x), \ m = \inf_{x \in \mathcal{X}} f(x) = \min_{x \in \mathcal{X}} f(x)$$

Proof. By Theorem 14.11 and its Corollary it follows that $f(\mathcal{X})$ is closed and bounded set (say, \mathcal{E}) of real numbers. So, if $M \in \mathcal{E}$ then $M \in \text{cl}\mathcal{E}$. Suppose $M \notin \mathcal{E}$. Then for any $\varepsilon > 0$ there is a point $y \in \mathcal{E}$ such that $M - \varepsilon < y < M$, for otherwise $(M - \varepsilon)$ would be an upper bound. Thus y is a limit point of \mathcal{E} . Hence, $y \in \text{cl}\mathcal{E}$ that proves the theorem.

The next theorem deals with the continuity property for inverse continuous one-to-one mappings.

Theorem 14.13 If $f : \mathcal{X} \to \mathcal{Y}$ is a continuous one-to-one mapping of a compact metric space \mathcal{X} into a metric space \mathcal{Y} then the inverse mapping $f^{-1} : \mathcal{Y} \to \mathcal{X}$ defined by

$$f^{-1}\left(f\left(x\right)\right) = x \in \mathcal{X}$$

is a continuous mapping too.

Proof. By Proposition 14.4, applied to f^{-1} instead of f, one can see that it is sufficient to prove that $f(\mathcal{V})$ is an open set of \mathcal{Y} for any open set $\mathcal{V} \subset \mathcal{X}$. Fixing a set \mathcal{V} we may conclude that the complement \mathcal{V}^c of \mathcal{V} is closed in \mathcal{X} and, hence, by Proposition 14.5 it is a compact. As the result, $f(\mathcal{V}^c)$ is a compact subset of \mathcal{Y} (14.11) and so, by Theorem 14.2, it is closed in \mathcal{Y} . Since f is one-to-one and onto, $f(\mathcal{V})$ is the compliment of $f(\mathcal{V}^c)$ and hence, it is open. This completes the proof. \blacksquare

Uniform continuity

Definition 14.17 Let $f : \mathcal{X} \to \mathcal{Y}$ be a mapping of a space \mathcal{X} into a metric space \mathcal{Y} . A mapping f is said to be

a) uniformly continuous on \mathcal{X} if for any $\varepsilon > 0$ there exists $\delta = \delta(\varepsilon) > 0$ such that $d_{\mathcal{Y}}(f(x), f(x')) < \varepsilon$ for all $x, x' \in \mathcal{X}$ for which $d_{\mathcal{X}}(x, x') < \delta$.

b) uniformly Lipschitz continuous on a (x, z)-set \mathcal{E} with respect to x, if there exists a positive constant $L_f < \infty$ such that

$$d_{\mathcal{Y}}(f(x,z), f(x',z)) \leq L_f d_{\mathcal{X}}(x,x')$$

for all $x, x', z \in \mathcal{E}$.

Remark 14.4 The different between the concepts of continuity and uniform continuity concerns two aspects:

- a) uniform continuity is a property of a function on a set, whereas continuity is defined for a function in a single point;
- b) δ, participating in the definition (14.50) of continuity, is a function of ε and a point p, that is, δ = δ (ε, p), whereas δ, participating in the definition (14.17) of simple continuity, is a function of ε only serving for all points of a set (space) X, that is, δ = δ (ε).

Evidently that any uniformly continues function is continuous but not inverse. The next theorem shows when both concepts coincide.

Theorem 14.14 If $f : \mathcal{X} \to \mathcal{Y}$ is a continuous mapping of a compact metric space \mathcal{X} into a metric space \mathcal{Y} then f is uniformly continuous on \mathcal{X} .

Proof. Continuity means that for any point $p \in \mathcal{X}$ and any $\varepsilon > 0$ we can associate a number $\delta(\varepsilon, p)$ such that

$$x \in \mathcal{X}, \ d_{\mathcal{X}}(x,p) < \delta(\varepsilon,p) \text{ implies } d_{\mathcal{Y}}(f(x),f(p)) < \varepsilon/2$$
 (14.54)

Define the set

$$\mathcal{J}(p) := \{ x \in \mathcal{X} : d_{\mathcal{X}}(x, p) < \delta(\varepsilon, p) / 2 \}$$

Since $p \in \mathcal{J}(p)$ the collection of all sets $\mathcal{J}(p)$ is an open cover of \mathcal{X} and by the compactness of \mathcal{X} there are a finite set of points $p_1, ..., p_n$ such that

$$\mathcal{X} \subset \mathcal{J}(p_1) \cup \cdots \cup \mathcal{J}(p_n) \tag{14.55}$$

Put

$$\tilde{\delta}(\varepsilon) := \frac{1}{2} \min \left\{ \delta(\varepsilon, p_1), ..., \delta(\varepsilon, p_n) \right\} > 0$$

Now let $x \in \mathcal{X}$ satisfies the inequality $d_{\mathcal{X}}(x,p) < \delta(\varepsilon)$. By the compactness (namely, by (14.55)) there is an integer m $(1 \le m \le n)$ such that $p \in \mathcal{J}(p_m)$ that implies

$$d_{\mathcal{X}}(x, p_m) < \frac{1}{2}\delta\left(\varepsilon, p_m\right)$$

and, as the result,

$$d_{\mathcal{X}}(x, p_m) \le d_{\mathcal{X}}(x, p) + d_{\mathcal{X}}(p, p_m) \le \tilde{\delta}(\varepsilon) + \frac{1}{2}\delta(\varepsilon, p_m) \le \delta(\varepsilon, p_m)$$

Finally, by (14.54)

$$d_{\mathcal{Y}}(f(x), f(p)) \le d_{\mathcal{Y}}(f(x), f(p_m)) + d_{\mathcal{Y}}(f(p_m), f(p)) \le \varepsilon$$

that completes the proof. \blacksquare

Remark 14.5 The alternative proof of this theorem may be obtained in the following manner: assuming that f is not uniformly continuous we conclude that there exists $\varepsilon > 0$ and the sequences $\{x_n\}, \{p_n\}$ on \mathcal{X} such that $d_{\mathcal{X}}(x_n, p_n) \xrightarrow[n \to \infty]{} 0$ but $d_{\mathcal{Y}}(f(x_n), f(p_n)) > \varepsilon$. The last is in a contradiction with Theorem 14.3.

Next examples shows that compactness is essential in the hypotheses of the previous theorems.

Example 14.6 If \mathcal{E} is a non compact in \mathbb{R} then

1. There is a continuous function on \mathcal{E} which is not bounded, for example,

$$f(x) = \frac{1}{x-1}, \ \mathcal{E} := \{x \in \mathbb{R} : |x| < 1\}$$

Here, \mathcal{E} is a non compact, f(x) is continuous on \mathcal{E} , but evidently unbounded. It is easy to check that it is not uniformly continuous.

2. There exists a continuous and bounded function on \mathcal{E} which has no maximum, for example,

$$f(x) = \frac{1}{1 + (x - 1)^2}, \ \mathcal{E} := \{x \in \mathbb{R} : |x| < 1\}$$

Evidently that

 $\sup_{x\in\mathcal{E}}f\left(x\right)=1$ whereas $\frac{1}{2}\leq f\left(x\right)<1$ and, hence, has no maximum on $\mathcal{E}.$

Continuity of a family of functions: equicontinuity

Definition 14.18 A family \mathbf{F} of functions f(x) defined on some xset \mathcal{E} is said to be **equicontinuous** if for any $\varepsilon > 0$ there exists a $\delta = \delta(\varepsilon)$, the same for all class \mathbf{F} , such that $d_{\mathcal{X}}(x,y) < \delta$ implies $d_{\mathcal{Y}}(f(x), f(y)) < \varepsilon$ for all $x, y \in \mathcal{E}$ and any $f \in \mathbf{F}$.

The most frequently encountered equicontinuous families \mathbf{F} occur when $f \in \mathbf{F}$ are uniformly Lipschitz continuous on $\mathcal{X} \subseteq \mathbb{R}^n$ and there exists a $L_f > 0$ which is a Lipschitz constant for all $f \in \mathbf{F}$. In this case $\delta = \delta(\varepsilon)$ can be chosen as $\delta = \varepsilon/L_f$.

The following claim can be easily proven.

Claim 14.5 If a sequence of continuous functions on a compact set $\mathcal{X} \subseteq \mathbb{R}^n$ is uniformly convergent on \mathcal{X} , then it is uniformly bounded and equicontinuous.

The next two assertions usually referred to as the Ascoli-Arzelà's theorems (see the reference in (Hartman 2002)). They will be used below for the analysis of Ordinary Differential Equations.

Theorem 14.15 (on the propagation, Ascoli-Arzelà 1883-1895) Let on a compact x-set of \mathcal{E} , the sequence of functions $\{f_n(x)\}_{n=1,2,...}$ be equicontinuous and convergent on a dense subset of \mathcal{E} . Then there exists a subsequence $\{f_{n_k}(x)\}_{k=1,2,...}$ which is uniformly convergent on \mathcal{E} .

Another version of the same fact looks as follows.

Theorem 14.16 (on the selection, Ascoli-Arzelà 1883-1895) Let on a compact x-set of $\mathcal{E} \subset \mathbb{R}^n$, the sequence of functions $\{f_n(x)\}_{n=1,2,\ldots}$ be uniformly bounded and equicontinuous. Then there exists a subsequence $\{f_{n_k}(x)\}_{k=1,2,\ldots}$ which is uniformly convergent on \mathcal{E} .

Proof. Let us consider the set of all rational numbers $\mathbf{R} \subseteq$ \mathcal{E} . Since **R** is countable, all of its elements can be designated by numbers, i.e., $\mathbf{R} = \{r_j\}$ (j = 1, ...). The numerical vector-sequence $\{f_n(r_1)\}_{n=1,2,\dots}$ is norm-bounded, say, $\|f_n(r_1)\| \leq M$. Hence, we can choose a convergent sequence $\{f_{n_k}(r_2)\}_{k=1,2,\dots}$ which is also bounded by the same M. Continuing this process we obtain a subsequence ${f_p(r_q)}_{p=1,2,\dots}$ that converges in a point $r_q, q = 1, 2, \dots$ Let $f_p :=$ $f_p(r_p)$. Show that the sequence $\{f_p\}$ is uniformly convergent on \mathcal{E} to a continuous function $f \in C(\mathcal{E})$. In fact, $\{f_p\}$ converges in any point of \mathbf{R} by the construction. To establish it convergence in any point of \mathcal{E} , it is sufficient to to show that for any fixed $x \in \mathcal{E}$ the sequence $\{f_p(x)\}\$ converges in itself. Since $\{f_p(x)\}\$ is equicontinuous, for any $\varepsilon > 0$ there exists $\delta = \delta(\varepsilon)$ such that for $||x - x'|| < \delta$ and $x, x' \in \mathcal{E}$ there is $||f_p(x) - f_p(x')|| < \varepsilon$. Choose r_j such that $||x - r_j|| < \delta$ that implies $||f_p(x) - f_p(r_j)|| < \varepsilon$. But the sequence $\{f_p(r_j)\}$ converges in itself. Hence, there is a number p_0 such that $||f_p(x) - f_{p'}(x')|| < \varepsilon$ whenever $p, p' > p_0$. So,

$$\|f_p(x) - f_{p'}(x')\| \le \|f_p(x) - f_p(r_j)\| + \\ \|f_p(r_j) - f_{p'}(r_j)\| + \|f_{p'}(r_j) - f_{p'}(x')\| \le 3\epsilon$$

Thus $\{f_p(x)\}$ converges at each $x \in \mathcal{E}$. It remains to prove that $\{f_p(x)\}$ converges uniformly on \mathcal{E} and, therefore, its limit f is from $C(\mathcal{E})$. Again, by the assumption on equicontinuity, one can cover the set \mathcal{E} with the finite δ -set containing, say, l subsets. In each of them select a rational numbers, say, $r_1, ..., r_l$. By the convergence of $\{f_p(x)\}$ there exists p_0 such that $||f_p(r_j) - f_{p'}(r_j)|| < \varepsilon$ whenever $p, p' > p_0$, so that

$$\|f_{p}(x) - f_{p'}(x)\| \le \|f_{p}(x) - f_{p}(r_{j})\| + \|f_{p}(r_{j}) - f_{p'}(r_{j})\| + \|f_{p'}(r_{j}) - f_{p'}(x)\| \le 3\epsilon$$

where j is selected in such a way that r_j belongs to the same δ -subset as x. Taking $p' \to \infty$, this inequality implies $||f_p(x) - f(x)|| \leq 3\varepsilon$ for all x from the considered δ -subset. but this exactly means the uniform converges of $\{f_p(x)\}$. Theorem is proven.

Connectedness

The definition of the connectedness of a set \mathcal{E} has been given in Definition 14.7. Here we will discuss its relation with the continuity property of a function f.

Lemma 14.2 If $f : \mathcal{X} \to \mathcal{Y}$ is a continuous mapping of a metric space \mathcal{X} into a metric space \mathcal{Y} , and if \mathcal{E} is a connected subset of \mathcal{X} , then $f(\mathcal{E})$ is connected.

Proof. On the contrary, assume that $f(\mathcal{E}) = \mathcal{A} \cup \mathcal{B}$ with non empty sets $\mathcal{A}, \mathcal{B} \subset \mathcal{Y}$ such that $\mathcal{A} \cap \mathcal{B} = \emptyset$. Put $\mathcal{G} = \mathcal{E} \cap f^{-1}(\mathcal{A})$ and $\mathcal{H} = \mathcal{E} \cap f^{-1}(\mathcal{B})$. Then $\mathcal{E} = \mathcal{G} \cup \mathcal{H}$ and both \mathcal{G} and \mathcal{H} are non empty. Since $\mathcal{A} \subset \operatorname{cl}\mathcal{A}$ it follows that $\mathcal{G} \subset f^{-1}(\operatorname{cl}\mathcal{A})$ and $f(\operatorname{cl}\mathcal{G}) \subset \operatorname{cl}\mathcal{A}$. Taking into account that $f(\mathcal{H}) = \mathcal{B}$ and $\operatorname{cl}\mathcal{A} \cap \mathcal{B} = \emptyset$ we may conclude that $\mathcal{G} \cap \mathcal{H} = \emptyset$. By the same argument we conclude that $\mathcal{G} \cap \operatorname{cl}\mathcal{H} = \emptyset$. Thus, \mathcal{G} and \mathcal{H} are separated that is impossible if \mathcal{E} is connected. Lemma is proven.

This theorem serves as an instrument to state the important result in \mathbb{R} which is known as the Bolzano theorem which concerns a global property of real-valued functions continuous on a compact interval $[a,b] \in \mathbb{R}$: if f(a) < 0 and f(b) > 0 then the graph of the function f(x) must cross the x - axis somewhere in between. But this theorem as well as other results, concerning the analysis of functions given on \mathbb{R}^n , will be considered in details below in the chapter named "*Elements* of *Real Analyses*".

Homeomorphisms

Definition 14.19 Let $f : S \to T$ be a function mapping points from one metric space (S, d_S) to another (T, d_T) such that it is one-to-one mapping or, in other words, $f^{-1} : T \to S$ exists. If additionally fis continuous on S and f^{-1} on T then such mapping f is called a **topological mapping** or **homeomorphism**, and the spaces (S, d_S) and $(f(S), d_T)$ are said to be **homeomorphic**.

It is clear from this definition that if f is homeomorphism then f^{-1} is homeomorphism too. The important particular case of a homeomorphism is, the so-called, an *isometry*, i.e., it is a one-to one continuous mapping which preserves the metric, namely, which for all $x, x' \in S$ keeps the identity

$$d_{\mathcal{T}}\left(f\left(x\right), f\left(x'\right)\right) = d_{\mathcal{S}}\left(x, x'\right)$$
(14.56)

14.2.6 The contraction principle and a fixed point theorem

Definition 14.20 Let \mathcal{X} be a metric space with a metric d. If φ maps \mathcal{X} into \mathcal{X} and if there is a number $c \in [0, 1)$ such that

$$d\left(\varphi\left(x\right),\varphi\left(x'\right)\right) \le cd\left(x,x'\right) \tag{14.57}$$

for all $x, x' \in \mathcal{X}$, then φ is said to be a contraction of \mathcal{X} into \mathcal{X} .

Theorem 14.17 (the fixed point theorem) If \mathcal{X} is a complete metric space and if φ is a contraction of \mathcal{X} into \mathcal{X} , then there exists one and only one point $x \in \mathcal{X}$ such that

$$\varphi(x) = x \tag{14.58}$$

Proof. Pick $x_0 \in \mathcal{X}$ arbitrarily and define the sequence $\{x_n\}$ recursively by setting $x_{n+1} = \varphi(x_n)$, $n = 0, 1, \dots$ Then, since φ is a contraction, we have

$$d(x_{n+1}, x_n) = d(\varphi(x_n), \varphi(x_{n-1})) \le cd(x_n, x_{n-1}) \le \dots \le c^n d(x_1, x_0)$$

Taking m > n and in view of the triangle inequality, it follows

$$d(x_m, x_n) \le \sum_{i=n+1}^m d(x_i, x_{i-1}) \le (c^{m-1} + \dots + c^n) d(x_1, x_0) \le c^n (c^{m-1-n} + \dots + 1) d(x_1, x_0) \le c^n (1-c)^{-1} d(x_1, x_0)$$

Thus $\{x_n\}$ is a Cauchy sequence, and since \mathcal{X} is a complete metric space, it should converge, that is, there exists $\lim_{n\to\infty} x_n := x$. And, since φ is a contraction, it is continuous (in fact, uniformly continuous). Therefore $\varphi(x) = \lim_{n\to\infty} \varphi(x_n) = \lim_{n\to\infty} x_n = x$. The uniqueness follows from the following consideration. Assume that there exists another point $y \in \mathcal{X}$ such that $\varphi(y) = y$. Then by (14.57) it follows $d(x, y) \leq cd(\varphi(x), \varphi(y)) = cd(x, y)$ which may only happen if d(x, y) = 0 that proves the theorem.

14.3 Resume

The properties of sets which remain invariant under every topological mapping is usually called the *topological properties*. Thus properties of being open, closed, or compact are topological properties.